# **Huayi Wang**

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#### Education

#### **Shanghai Jiao Tong University**

B.Eng. in Artificial Intelligence • GPA: 3.90/4.3; Rank: 22/92

Shanghai, China

Aug. 2022 - Present

### Research Interests

My current research is centered on Robot Learning and Control, with a specific focus on Humanoid Whole-Body Control. I am dedicated to developing effective robot learning-based training methods that prioritize agility, robustness, and safety.

## Research Experience \_\_\_

#### **Shanghai Jiao Tong University**

RESEARCH ASSITANT AT APEX LAB, ADVISED BY PROF. WEINAN ZHANG

• Research Topics: Reinforcement Learning, LLM Agent.

Shanghai, China

Dec.2023 - Jul.2024

#### Shanghai Artificial Intelligence Laboratory

INTERN AT INTERN ROBOTICS, ADVISED BY DR. JIANGMIAO PANG AND DR. JINGBO WANG

• Research Topics: Robot Learning, Humanoid Locomotion Control, Reinforcement Learning.

Shanghai, China

# Aug.2024 - Present

## **Publications**

(\*Equal Contribution, †Corresponding Author)

CONFERENCE PROCEEDINGS

#### [C3] BeamDojo: Learning Agile Humanoid Locomotion on Sparse Footholds

Huayi Wang, ZiRui Wang, Junli Ren, Qingwei Ben, Tao Huang, Weinan Zhang†, Jiangmiao Pang† Robotics: Science and Systems (RSS), 2025 (Oral Presentation) [Paper] [Website]

#### [C2] Learning Humanoid Standing-up Control across Diverse Postures

Tao Huang, Junli Ren, Huayi Wang, ZiRui Wang, Qingwei Ben, Muning Wen, Xiao Chen, Jianan Li, Jiangmiao Pang† Robotics: Science and Systems (**RSS**), 2025 (Outstanding Systems Paper Award Finalist - Top 4) [Paper] [Website] [Code]

#### [C1] Diversity-Aware Self-Paced Data Selection for LLM Fine-Tuning

Yingxuan Yang, **Huayi Wang**, Muning Wen, Xiaoyun Mo, Qiuying Peng, Jun Wang, Weinan Zhang† European Conference on Artificial Intelligence (**ECAI**), 2025 [Paper]

**PREPRINTS** 

#### [P4] PhysHSI: Towards a Real-World Generalizable and Natural Humanoid-Scene Interaction System

Huayi Wang\*, Wentao Zhang\*, Runyi Yu\*, Tao Huang, Junli Ren, Feiyu Jia, Zirui Wang, Xiaojie Niu, Xiao Chen, Jiahe Chen, Qifeng Chen†, Jingbo Wang†, Jiangmiao Pang† Under Review, 2025 [Paper] [Website] [Code]

#### [P3] Towards Adaptable Humanoid Control via Adaptive Motion Tracking

Tao Huang, Huayi Wang, Junli Ren, Kangning Yin, Zirui Wang, Xiao Chen, Feiyu Jia, Wentao Zhang, Junfeng Long, Jingbo Wangt, Jiangmiao Pangt

Under Review, 2025 [Paper] [Website] [Code]

#### [P2] Humanoid Goalkeeper: Learning from Position Conditioned Task-Motion Constraints

Junli Ren\*, Junfeng Long\*, Tao Huang, **Huayi Wang**, Zirui Wang, Feiyu Jia, Wentao Zhang, Jingbo Wangt, Ping Luot, Jiangmiao Pang†

Under Review, 2025 [Paper] [Website] [Code]

#### [P1] VB-Com: Learning Vision-Blind Composite Humanoid Locomotion Against Deficient Perception

Junli Ren, Tao Huang, Huayi Wang, ZiRui Wang, Qingwei Ben, Jiangmiao Pangt, Ping Luot Under Review, 2025 [Paper] [Website]

OCTOBER 23, 2025 HUAYI WANG · RESUME

# Honors & Awards \_\_\_\_\_

RSS Best Systems Paper Award Finalist Top 4 of accepted papers. [Link]	2025
<b>SenseTime Scholarship</b> 30 undergraduate Al researchers nationwide. [Link]	2025
<b>Guozhi honor class</b> Top 20% of AI honor class, held by Prof. Xiaoou Tang. [Link]	2024
SJTU undergraduate C-level scholarship	2023
Outstanding members of the Communist Youth League	2022

# Skills\_\_\_\_\_

**Programming** Python, C/C++, LaTeX, JAVA, MATLAB

**Frameworks** PyTorch, NumPy, Git, Anaconda, ROS, OpenCV, Linux

**Languages** Mandarin (Native), English